

en/StickSetup/Mode4

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[StickSetup](#)

MODE 4

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Here are the functions described which can be adjusted by different positions of the control stick in Mode 4.

Assignment of the sticks for MODE 4



Description of the stick assignment for MODE 4

<p>Function =></p>	<p>Calibration of the ACC (One time necessary. The Kopter must stand straight.)</p>
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw right / Nick middle / Roll middle</p>





<p>Function =></p>	<p>Calibration of the Gyros (Before every Start and after disconnecting the power supply.)</p>
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw left / Nick middle / Roll middle</p>



<p>Function =></p>	<p>Start to calibrate the Compass HINT: First pull Nick down. (The calibration is described here: Calibration of the compass)</p>
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw left / Nick down / Roll middle</p>





<p>Function =></p>	<p>Start of the engines</p>	
<p>Description of the stick assignment =></p>	<p>Throttle down / Yaw right / Nick middle / Roll middle</p>	
<p>Function =></p>	<p>Stop of the engines</p>	
<p>Description of the stick assignment =></p>	<p>Throttle down / Yaw left / Nick middle / Roll middle</p>	

<p>Function =></p>	<p>Selection Setting 1</p>
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw left / Nick middle / Roll left</p>



<p>Function =></p>	<p>Selection Setting 2</p>
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw left / Nick up / Roll left</p>



<p>Function =></p>	<p>Selection Setting 3</p>	
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw left / Nick up / Roll middle</p>	
<p>Function =></p>	<p>Selection Setting 4</p>	
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw left / Nick up / Roll right</p>	

Function =>	Selection Setting 5	
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw left / Nick middle / Roll right</p>	