

en/StickSetup/Mode1

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[StickSetup](#)

MODE 1

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Here are the functions described which can be adjusted by different positions of the control stick in Mode 1.



Description of the stick assignment for MODE 1	
<p>Function =></p>	<p>Calibration of the ACC (One time necessary. The Kopter must stand straight.)</p>
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw right / Nick middle / Roll middle</p>





<p>Function =></p>	<p>Calibration of the Gyros (Before every Start and after disconnecting the power supply.)</p>
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw left / Nick middle / Roll middle</p>



<p>Function =></p>	<p>Start to calibrate the Compass Hint: First pull Nick down. (The calibration is described here: Calibration of the compass)</p>
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw left / Nick down / Roll middle</p>



<p>Function =></p>	<p>Start the engines</p>	
<p>Description of the stick assignment =></p>	<p>Throttle down / Yaw right / Nick middle / Roll middle</p>	
<p>Function =></p>	<p>Stop the engines</p>	
<p>Description of the stick assignment =></p>	<p>Throttle down / Yaw left / Nick middle / Roll middle</p>	

Function =>	Selection Setting 1
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw left / Nick middle / Roll left</p>
Function =>	Selection Setting 2
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw left / Nick up / Roll left</p>



<p>Function =></p>	<p>Selection Setting 3</p>
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw left / Nick up / Roll middle</p>



<p>Function =></p>	<p>Selection Setting 4</p>
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw left / Nick up / Roll right</p>



Function =>	Selection Setting 5	
<p>Description of the stick assignment =></p>	<p>Throttle up / Yaw left / Nick middle / Roll right</p>	