# en/CalibrateAltitude

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## 1 Calibrate barometric altitude sensor

!!! The following settings apply only to FlightCtrl V3.0 - Older FlightCtrl versions can not be calibrated !!!

The barometric height sensor is required for automatic holding of the height of the MikroKopter. The sensor should be calibrated once. Thus, the sensor is working properly even under temperature fluctuations (factor = x cm per  $^{\circ}$ C).

If the sensor is not calibrated, the copter can vary in height.

Recalibration of the height sensor is not usually necessary.

**INFO:** Before the <u>FlightCtrl</u> was delivered, the altitude sensor has already been calibrated.

### **1.1 Calibration**

For calibration of the barometric height sensor, a heat source is required. This can be e.g. a lamp or a hair dryer.

**IMPORTANT:** The heating MUST be SLOW.

### The calibration is done in a few steps:

Step	Example view
<b>Step 1</b> The heat source (switched off) is positioned over the <u>FlightCtrl</u> . (You can remove the GPS if you want - then heating is a little faster.)	P
Step 2   Connect the copter now with your computer.   (via MK-USB or wireless)   Start the KopterTool and power up the copter.   (also switch on the transmitter)	

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# 2 Check calibration / manual adjustment

In the window "Temperature settings" you can check the stored value and also change it.

!! If you change the value manually you can also have a negative effect during altitude hold - better use the automatic calibration!!!

Step	Example view
Beside the button "Settings" you find a smal arrow down. With this arrow you can open the window "Temperature settings".	