

## **en/StickSetup/Mode4**

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[StickSetup](#)


**MODE 4**

- [deutsch](#)
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Here are the functions described which can be adjusted by different positions of the control stick in Mode 4.

Assignment of the sticks for MODE 4



Description of the stick assignment for MODE 4		
Function =>	Calibration of the ACC  (One time necessary. The Kopter must stand straight.)	
Description of the stick assignment =>	Throttle up / Yaw right / Nick middle / Roll middle	

<b>Function</b> =>	<b>Calibration of the Gyros</b>  (Before every Start and after disconnecting the power supply.)
<b>Description of the stick assignment</b> =>	Throttle up / Yaw left / Nick middle / Roll middle



<b>Function</b> =>	<b>Start to calibrate the Compass</b>  <b>HINT:</b> First pull Nick down.  (The calibration is described here: <a href="#">Calibration of the compass</a> )
<b>Description of the stick assignment</b> =>	Throttle up / Yaw left / Nick down / Roll middle





<b>Function</b> =>	<b>Start of the engines</b>
<b>Description of the stick assignment</b> =>	Throttle down / Yaw right / Nick middle / Roll middle
<b>Function</b> =>	<b>Stop of the engines</b>
<b>Description of the stick assignment</b> =>	Throttle down / Yaw left / Nick middle / Roll middle



Function =>	Selection Setting 1
Description of the stick assignment =>	Throttle up / Yaw left / Nick middle / Roll left
Function =>	Selection Setting 2
Description of the stick assignment =>	Throttle up / Yaw left / Nick up / Roll left





Function =>	Selection Setting 3
Description of the stick assignment =>	Throttle up / Yaw left / Nick up / Roll middle
Function =>	Selection Setting 4
Description of the stick assignment =>	Throttle up / Yaw left / Nick up / Roll right



Function =>	Selection Setting 5
Description of the stick assignment =>	Throttle up / Yaw left / Nick middle / Roll right

